Percolation in multiplex networks with overlap

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(Received 24 July 2013; revised manuscript received 23 October 2013; published 25 November 2013)

From transportation networks to complex infrastructures, and to social and communication networks, a large variety of systems can be described in terms of multiplexes formed by a set of nodes interacting through different networks (layers). Multiplexes may display an increased fragility with respect to the single layers that constitute them. However, so far the overlap of the links in different layers has been mostly neglected, despite the fact that it is an ubiquitous phenomenon in most multiplexes. Here, we show that the overlap among layers can improve the robustness of interdependent multiplex systems and change the critical behavior of the percolation phase transition in a complex way.

DOI: 10.1103/PhysRevE.88.052811 PACS number(s): 89.75.Hc, 05.70.Fh, 64.60.ah, 64.60.aq

I. INTRODUCTION

In the last decade, we have gained a deep understanding of the interplay between the topology of single complex networks [1–3] and the behavior of critical phenomena occurring on them [4,5]. Recently, it has become clear that in order to fully investigate the properties of a large variety of complex systems such as energy supply networks [6], complex infrastructures [7–11], social networks [12], climatic systems [13], and brain networks [14], it is necessary to consider their multilayer structure [15]. Each layer corresponds to a network with a specific function, but the entire complex system requires multiple layers operating in a coupled way and forming an interacting set of networks. For example, analyses of the disruptions provoked by an earthquake to large infrastructures show the relevance of interdependence among power transmission and telecommunications [16] and the different resilience of coupled networks such as the power grid and the water system [17].

An important and ubiquitous example of multilayer networks is a multiplex where the same nodes are linked by different networks (layers). A multiplex is formed by a set of $N$ nodes and $M$ layers. Every node is represented in every layer, and every layer is formed by a network of interactions (links) between the nodes. For instance, multiplexes are good descriptions of social networks, where the nodes represent agents and the different layers correspond either to different types of interaction (such as family, work, or friendship ties) [12] or to different means of communication (email, chat, mobile phone, etc.) [18]. Other examples of multiplexes can be found in transportation networks, where cities can be connected by roads, railways, waterways, or airline connections [10,11,19], or brain networks where different regions of the brain belong at the same time to the functional network of brain activity and to the structural brain network [14].

In the last years, interest on multiplexes has been growing both on the theoretical side, and on the empirical side of multiplex data analysis. In fact, different models of multiplex structure have been formulated [20–23], critical phenomena and dynamical processes have been characterized on multiplex structures [6,24–40], and finally new structural measures have been introduced and evaluated in large multiplex data sets [10–13]. The theoretical interest has been partly sparked by the discovery [6,24–26] that the robustness properties of a multiplex formed by interdependent networks is strongly affected by its multilayer structure. In fact, a multiplex can be much more fragile than single networks and its functionality can be affected significantly by cascades of node failures [6,24,26]. In this context, the mutually connected giant component (MCGC) plays a pivotal role. The MCGC of a multiplex is the extensive component where every pair of nodes is connected in every layer by at least one path formed by nodes inside the MCGC. If a fraction $1 − p$ of nodes is removed from a multiplex with a MCGC, the size of the MCGC is reduced. At some value of $p$, a critical point is reached where a first order hybrid transition is observed and the MCGC abruptly drops from a finite value to zero [6,24–26,30–32].

Despite the interesting theoretical behavior, analysis of the empirical side offers another observation not yet addressed by the theory, which is that many multiplexes [11,12,27] are formed by correlated networks characterized by a significant overlap of the links. For example, in social networks it is common for two friends to communicate both via email and via mobile phone, or in transportation networks two cities connected by a main road are likely to be connected also by a railway. Given such empirical findings, the theory of multiplex networks can not be complete until the effects of link overlap in the multiplex robustness properties (characterized by the MCGC) are understood.

Our aim is not to address a specific application, but give instead a general theoretical approach that can include edge overlap in the study of percolation under random damage. Percolation is perhaps the simplest model of robustness and stability, but it constitutes a first step in dealing with more complex models and even dynamical processes occurring on the network. Therefore, introducing a formalism with edge overlap in percolation on multiplex networks should be seen as an important building block of the science of complex networks.

In this paper, we apply this formalism to the case of two- and three-layer Poisson graphs and calculate the phase diagrams of the models. We show that edge overlap can significantly enhance the robustness properties of the multiplex. We also
show that a multiplex formed by more than two layers presents a very rich phase diagram with high order critical points, characterizing the increased complexity of this percolation problem.

In Sec. II, we introduce the notation of multiplexes with edge overlap. In Sec. III, we formulate a general framework to characterize the emergence of the MCGC. In Sec. IV, we calculate the phase diagrams of percolation on two- and three-layer Poisson graphs, and in Sec. V we draw the conclusion of this work.

II. MULTIPLEX WITH OVERLAP

Consider a multiplex formed by $N$ labeled nodes $i = 1, 2, \ldots, N$ and $M$ layers. We can represent the multiplex as described in Ref. [15]. To this end, we indicate by $\mathcal{G} = (\mathcal{G}^1, \ldots, \mathcal{G}^\alpha, \ldots, \mathcal{G}^M)$ the set of all the networks $\mathcal{G}^\alpha$ at layer $\alpha = 1, 2, \ldots, M$ forming the multiplex. Each of these networks has an adjacency matrix with matrix elements $a_{ij}^\alpha = 1$ if there is a link between node $i$ and node $j$ in layer $\alpha$ and zero otherwise.

Useful concepts to characterize multiplex structure are multilinks and multidegrees recently defined in Ref. [22]. Let us consider the vector $\vec{m} = (m_1, \ldots, m_\alpha, \ldots, m_M)$ in which every element $m_\alpha$ can take only two values $m_\alpha = 0, 1$. We define a multilink, and we represent it with $\vec{m}$, as the set of links connecting a given pair of nodes in the different layers of the multiplex and connecting them in the generic layer $\alpha$ only if $m_\alpha = 1$. Multilinks are mutually exclusive, i.e., any pair of nodes $(i, j)$ can be linked only by one multilink $\vec{m}$, that we call $\vec{m}^{ij}$. In Fig. 1, we show an example of a multiplex where nodes $(i, j)$ are linked by a multiplex $(1, 1, 0)$ and nodes $(r, l)$ are linked by a multilink $(1, 1, 1)$.

Note how the introduction of the multilink now makes explicit the notion of overlap of the links: the links $(i, j)$ in the layers $\alpha_1, \ldots, \alpha_l$ overlap if the nodes $i$ and $j$ are joined by a multilink $\vec{m} = \vec{m}^{ij}$ and $m_{ij}^\alpha = \ldots = m_{ij}^\alpha = 1$.

For a multiplex it is possible to define a set of multiadjacency matrices of elements by setting $A_{ij}^\alpha = 1$ if node $i$ is linked to node $j$ by a multilink $\vec{m}$ and $A_{ij}^\alpha = 0$ otherwise. In other words, every element $A_{ij}^\alpha$ not only depends on the node pair $(i, j)$ as in classical adjacency matrices, but it is also a function of the generic multilink $\vec{m}$. These multiadjacency matrices can be defined in terms of the adjacency matrices $(a_{ij}^\alpha)$ on each layer $\alpha$, i.e., for each $\vec{m} = \{0, 1\}^M$,

$$A_{ij}^{\vec{m}} = \prod_{\alpha=1}^{M} \left( a_{ij}^\alpha m_\alpha + (1 - a_{ij}^\alpha)(1 - m_\alpha) \right). \quad (1)$$

The expression in the square brackets (in an unweighted network) can only be zero or one. It equals one only when the components of $\vec{m}$ match the actual presence of an $(i, j)$ link on the layer $\alpha$. Otherwise, the expression is zero and correctly represents the absence of a multilink of given type $\vec{m}$ between $i$ and $j$. The number of multilinks is $2^M$ but the elements of the multiadjacency matrices are not all independent. In fact, they satisfy the relation

$$\sum_{\vec{m} \in \{0,1\}^M} A_{ij}^{\vec{m}} = 1, \quad (2)$$

where the sum is over the set of all possible multilinks. Since the elements of the multiadjacency matrices $A_{ij}^{\vec{m}}$ are either zero or one, the condition given by Eq. (2) implies that between any pair of nodes $(i, j)$ there is a single multilink that we indicate with $\vec{m}^{ij}$. Therefore, only $2^M - 1$ adjacency matrices are independent. In most multiplex networks, the number of layers is finite, therefore the exponential number of multilinks is not an important limitation to this approach. Moreover, our framework can be easily generalized to the case of multiplexes with a large number of layers $M$ in which only a few types of multilinks are allowed.

Finally, we define the multidegree with respect to $\vec{m}$ of a node $i$, $k_i^{\vec{m}}$, as the total number of multilinks $\vec{m}$ connected to node $i$, i.e.,

$$k_i^{\vec{m}} = \sum_{j=1}^{N} A_{ij}^{\vec{m}}. \quad (3)$$

In the specific case of a duplex ($M = 2$) we have $k_i^{(1,1)} = o_i$, where $o_i = \sum_j a_{ij}^{(1,1)}$ is the local overlap of node $i$, i.e., the total number of nodes $j$ linked to node $i$ both in layer 1 and in layer 2. In general, for a multiplex of $M$ layers the multidegree $k_i^{\vec{m}}$ can be considered as a high order measure of local overlap as long as $\sum_\alpha m_\alpha > 0$.

This framework encapsulates two particular cases, which are already known to the scientific community. First, let us consider the case of fully overlapping multiplexes, where all links are the same in all layers. In this case, we recover classical percolation with a continuous second order phase transition. Second, we may consider the case where edges on different layers are totally uncorrelated. As we are considering configuration model graphs on each layer, the multiplex consists of a random coupling of locally treelike, sparse random graphs [33]. Therefore, the probability of edge overlap vanishes as $N \to \infty$. It has been recently shown that in this case the phase transition is discontinuous [30]. In general, instead, one needs to consider overlap effects when designing or studying the fragility of multiplexes. Our formalism, and in particular the concept of multilink, can be very helpful, giving us a fully controllable tool to study the problem.
III. EMERGENCE OF THE MUTUALLY CONNECTED GIANT COMPONENT (MCGC)

As we mention in the Introduction, the MCGC of a multiplex is the extensive component where every pair of nodes is connected in every layer by at least one path formed by nodes inside the MCGC. Then, we can consider the behavior of the size of the MCGC in a multiplex as a fraction $1 - p$ of nodes is removed. If there is no link overlap, at a critical value of $p$, a first order hybrid transition is observed and the MCGC abruptly drops from a finite value to zero [6,24–26,30,31].

Our goal is to characterize the effect of link overlap on how the mutually connected giant component (MCGC) changes as a function of $p$ (the fraction of remaining nodes). Specifically, we will follow and extend the approach developed by Son et al. [31] for studying the percolation on two interdependent networks without overlap. First of all, we observe that a node $i$ belongs to the mutually connected giant component of the multiplex networks if and only if the following $M$ conditions are met simultaneously: for every layer $\alpha = 1, 2, \ldots, M$ at least one of the neighbor nodes of $i$ in network $\alpha$ belongs to the mutually connected giant component of the interdependent networks. We consider a treelike multiplex, i.e., a multiplex in which the combined network of all the layers [i.e., the network of adjacency matrix $B_{ij} = \theta(\sum_{\alpha=1}^{M} a_{ij}^{(\alpha)})$, where $\theta(x) = 1$ if $x > 0$ otherwise $\theta(x) = 0$] is locally treelike. According to the above recursive definition of the MCGC, on a locally treelike multiplex we can determine if a node belongs to the MCGC by an “epidemic spreading” process [31].

Let $s_{i} = 0, 1$ indicate if a node is removed or not from the network and let $s_{i} = 0, 1$ be the indicator function that the node $i$ is in the mutually connected giant component. The value of $s_{i}$ is determined by the “messages” that the neighboring nodes send to node $i$. We denote these “messages” as $\sigma^{j \leftarrow i}_{\alpha}$. The value of the message is set to one $\sigma^{j \leftarrow i}_{\alpha} = 1$ if and only if the following two conditions are satisfied:

(a) node $j$ is a neighbor of node $i$ with a multilink $\vec{m}^{j \leftarrow i}$ connecting them such that $\sum_{\alpha} m^{j \leftarrow i}_{\alpha} > 0$;

(b) node $j$ belongs to the mutually connected giant component even if the multilink $\vec{m}^{j \leftarrow i}$ between node $j$ and node $i$ is removed from the multiplex.

Otherwise, we will have $\sigma^{j \leftarrow i}_{\alpha} = 0$.

In a locally treelike multiplex, the value of $s_{i}$ and $\sigma^{j \leftarrow i}_{\alpha}$ satisfies the following message-passing relations:

\[
s_{i} = s_{i} \prod_{\alpha=1}^{M} \left[ 1 - \prod_{j \in N_{\alpha}(i)} (1 - \sigma^{j \leftarrow i}_{\alpha}) \right], \tag{4}
\]

\[
\sigma^{j \leftarrow i}_{\alpha} = s_{j} \prod_{\alpha=1}^{M} \left[ 1 - \prod_{l \in N_{\alpha}(j) \setminus i} (1 - \sigma^{l \leftarrow j}_{\alpha}) \right], \tag{5}
\]

where $N_{\alpha}(i)$ indicates the set of nodes that are neighbor of node $i$ in layer $\alpha$. The expression within square brackets in Eq. (4) is one only if on layer $\alpha$ at least one of the neighbors $j$ of node $i$ is connected to the MCGC by an edge other than the $(i,j)$ edge, otherwise is zero. Equation (5) has been written using the same logic, but taking now into consideration that $j$ is required to be in the MCGC by connecting to a neighbor $l$ which must be different from $i$. This is calculated by subtracting from one the probability that all the neighbors $j$ of $i$ are not attached to the MCGC.

Let us now consider Eq. (5), by using the formula

\[
\prod_{\alpha=1}^{M} (1 - x_{\alpha}) = \sum_{\vec{r}} (-1)^{\vec{r}} x_{\alpha}^{1} \cdots x_{\alpha}^{M}.
\]

where $\vec{r} = (r_{1}, r_{2}, \ldots, r_{\alpha}, \ldots, r_{M})$ with $r_{\alpha} = 0$, and where the sum $\sum_{\vec{r}}$ is over all possible vectors $\vec{r}$. We can expand the multiplications and write

\[
\sigma^{j \leftarrow i}_{\alpha} = s_{j} \sum_{\vec{r}} (-1)^{\vec{r}} \prod_{\alpha=1}^{M} \prod_{l \in N_{\alpha}(j) \setminus i} (1 - \sigma^{l \leftarrow j}_{\alpha})^{r_{\alpha}}. \tag{6}
\]

By observing that for each node $l$ neighboring node $j$ in layer $\alpha$ we should necessarily have $m^{j \leftarrow l}_{\alpha} = 1$ and that $\sigma^{j \leftarrow l}_{\alpha} = 0$, it is possible to swap the two products in Eq. (6) and show that

\[
\sigma^{j \leftarrow i}_{\alpha} = s_{j} \prod_{\vec{r}} (1 - \sigma^{j \leftarrow i}_{\alpha})^{r_{\alpha}} - m^{j \leftarrow i}_{\alpha} \prod_{\vec{r}} (1 - \sigma^{j \leftarrow i}_{\alpha})^{r_{\alpha}}. \tag{7}
\]

Similarly, we can show that

\[
\sigma_{i} = s_{i} \sum_{\vec{r}} (1 - \sigma_{i}^{\vec{r}}) \prod_{l = 1, l \neq i}^{N} (1 - \sigma_{l}^{\vec{r}}) \prod_{\alpha=1}^{M} m^{j \leftarrow i}_{\alpha} \tag{8}
\]

Let us now consider a multiplex belonging to the multiplex ensemble [22] characterized by a given multidegree distribution and no degree-degree (multidegree-multidegree) correlations. We can construct a network in this ensemble by extending the configuration model to networks with multidegrees. To this end, we draw the multidegree sequence $\{k^{(\alpha)}_{m}\}$ from a multidegree distribution $P(k^{(\alpha)}_{m})$. We then attach $k^{(\alpha)}_{m}$ stubs of type $\vec{m}$ such that $\sum_{\alpha} k^{(\alpha)}_{m} > 0$ to each node $i$. Finally, we randomly match the stubs of the same type of multilinks belonging to different nodes. In this ensemble, the probability $P(\vec{G})$ of a multiplex $\vec{G}$ is given by

\[
P(\vec{G}) = \prod_{i} \prod_{\vec{m} \neq 0} \left( \frac{k^{(\alpha)}_{m} k^{(\alpha)}_{\vec{m}}}{(k^{(\alpha)}_{m} N)^{\alpha}} \right)^{A_{\vec{m}}^{(\alpha)}} \left[ 1 - \sum_{\vec{m} \neq 0} \frac{k^{(\alpha)}_{m} k^{(\alpha)}_{\vec{m}}}{(k^{(\alpha)}_{m} N)^{\alpha}} A_{\vec{m}}^{(\alpha)} \right], \tag{9}
\]

where we have assumed that the multidegrees $k^{(\alpha)}_{m} < \sqrt{(k^{(\alpha)}_{m} N)}$, $\forall \vec{m} \neq 0$, and we have indicated with $\langle k^{(\alpha)}_{m} \rangle$ the average of the multidegrees $m$ present in the network. The condition on the multidegrees imposes a “multidegree structural cutoff” that ensures the fact that in the multiplex the multidegrees of linked nodes are not correlated. We assume that the nodes are removed with probability $(1 - p)$, and that therefore the sequence $\{s_{i}\}$ indicating if the node $i$ is removed $(s_{i} = 0)$ or not $(s_{i} = 1)$ has probability

\[
P(s_{i}) = \prod_{i=1}^{N} \left[ p s_{i} + (1 - p)(1 - s_{i}) \right]. \tag{10}
\]

We define $S_{0}$ the probability that following a multilink $\vec{m}$ (with $\sum_{\alpha} n_{\alpha} > 0$) we reach a node in the MCGC in a multiplex in this ensemble. Since $\sigma^{j \leftarrow i}_{\alpha} = 0, 1$, the probability $S_{0}$ that a
random message in the multiplex is equal to one, i.e., $S_0 = P(\sigma_{r,j}^l = 1 | \mathbf{m}^i) = \bar{n}$ is equal to the average

$$S_0 = \left( \delta(\mathbf{m}^i, \bar{n}) \alpha_{\mathbf{m}^i, \bar{n}}^0 \right),$$  

(11)

where $\delta(\mathbf{m}^i, \bar{n}) = 1$ if $\mathbf{m}^i = \bar{n}$ and $\delta(\mathbf{m}^i, \bar{n}) = 0$ otherwise, and where we use the notation

$$f_{ij}(\mathbf{m}^i) = \sum_{\mathbf{G}} P(\mathbf{G}) \sum_{\{s_i\}} \sum_{i,j} \delta(\mathbf{m}^i, \bar{n}) f_{ij}(\mathbf{m}^i)$$

(12)

for any function $f_{ij}(\mathbf{m}^i)$. The equation for $S_0$ can be derived from the recursive Eq. (7) as follows:

$$S_0 = \left( \delta(\mathbf{m}^i, \bar{n}) \right) \left( -1 \right)^{\sum_{r,j} \sum_{l=1}^{N} \delta(\mathbf{m}^i, \bar{n}) \sum_{\mathbf{m}^r} \mathbf{m}^r \mathbf{m}^i \right).$$

(13)

The probability that a random multilink $\bar{n} = \mathbf{m}^i$ of the network will have a node at its end (node $j$ with multidegree sequence $(k^m)$) is given by $k^m P((k^m))/k^m$. If the node $j$ has multidegrees $k^m$, it will have a number $k^m$ of incoming messages from multilinks $\mathbf{m}$. When calculating the average in Eq. (13), we have to consider all the messages $\sigma_{\mathbf{m}^i, \bar{n}}^0$ incoming to node $j$ except the message coming from node $i$ that is given by $\sigma_{\mathbf{m}^i, \bar{n}}^0$, i.e., it is of type $\bar{n}$. Therefore, since on a tree-like network the messages sent by any two neighbors are independent, we have that Eq. (13) becomes

$$S_0 = p \sum_{\{k^m\}} k^m P((k^m)) \sum_{\bar{r}} \left( -1 \right)^{\sum_{r,j} \sum_{l=1}^{N} \delta(\mathbf{m}^i, \bar{n}) \sum_{\mathbf{m}^r} \mathbf{m}^r \mathbf{m}^i \right)$$

(14)

where $P((k^m))$ is the multidegree distribution, the sum $\sum_{\bar{r}}$ is over all the possible vectors $\bar{r} = (r_1, r_2, \ldots, r_M)$. Finally, using the definition of $S_0$ given in Eq. (11), we obtain

$$S_0 = p \sum_{\{k^m\}} k^m P((k^m)) \sum_{\bar{r}} \left( -1 \right)^{\sum_{r,j} \sum_{l=1}^{N} \delta(\mathbf{m}^i, \bar{n}) \sum_{\mathbf{m}^r} \mathbf{m}^r \mathbf{m}^i \right)$$

(15)

where we have used the same notation as in Eq. (14). Similarly, the probability $S = P(\sigma_1 = 1)$ that a random node belongs to the MCGC can be expressed as

$$S = \sum_{\mathbf{G}} P(\mathbf{G}) \sum_{\{s_i\}} \sum_{i} \frac{\sigma_i}{N}.$$

(16)

Starting from Eq. (8) and using similar steps used to derive Eq. (15), it can be shown that $S$ must satisfy the following equation:

$$S = p \sum_{\{k^m\}} P((k^m)) \sum_{\bar{r}} \left( -1 \right)^{\sum_{r,j} \sum_{l=1}^{N} \delta(\mathbf{m}^i, \bar{n}) \sum_{\mathbf{m}^r} \mathbf{m}^r \mathbf{m}^i \right)$$

(17)

where we have used the same notation as in Eq. (14).

We note here that the Eqs. (17)–(15) are generalizations of Eq. (8) in Ref. [25], when the overlap of the links is significant. Moreover, we observe that here, as in other percolation problems [32], the quantities $S_0$ and $S$ are self-averaging, i.e., we expect that the network average of the messages and the values of $\sigma_i$ converge, in the large network limit, to $S_0$ and $S$, respectively.

An interesting case emerges when the degree distribution of the multidegrees is factorizable, i.e., $P((k^m)) = \prod_m p_{k^m}$ where $p_{k^m}$ is the degree distribution of the multidegree $k^m$. In this case, we can introduce the following generating functions of the real (scalar) variable $z$:

$$G_0^0(z_m) = \sum_{k^m} p_{k^m} z_m^k,$$

$$G_1^1(z_m) = \sum_{k^m} \frac{k^m}{k_m^m} p_{k^m} z_m^{k^m - 1}.$$

(18)

Therefore, Eqs. (17) and (15) now read as

$$S = p \sum_{\{k^m\}} \sum_{\bar{r}} \left( -1 \right)^{\sum_{r,j} \sum_{l=1}^{N} \delta(\mathbf{m}^i, \bar{n}) \sum_{\mathbf{m}^r} \mathbf{m}^r \mathbf{m}^i \right) \prod_{\mathbf{m}} G_0^0(1 - S_0),$$

(19)

$$S^0 = p \sum_{\{k^m\}} \sum_{\bar{r}} \left( -1 \right)^{\sum_{r,j} \sum_{l=1}^{N} \delta(\mathbf{m}^i, \bar{n}) \sum_{\mathbf{m}^r} \mathbf{m}^r \mathbf{m}^i \right) \prod_{\mathbf{m}} G_0^0(1 - S_0),$$

(20)

where $f(\bar{r}) = 1$ if $\sum_{\mathbf{m}} r_\alpha n_\alpha > 0$ and $f(\bar{r}) = 0$ otherwise.

IV. SPECIFIC EXAMPLES

A. Two Poisson layers with overlap

We consider now the case of a duplex $M = 2$ in which the multidegree distributions are Poisson with means governed by the real parameters $c^1$ and $c^2$ (note that, here and in the following, 1 and 2 in $c^1$ and $c^2$ are indices, not exponents). So, we assume $k(1) = c^1$ and $k(2) = c^2$. Due to the properties of the Poisson distribution, from Eq. (17) we have $S = S_{00} = S_{10} = S_{11}$, where $S$ satisfies the equation

$$S = p \left[ 1 - 2e^{-c^1 + c^2}S + e^{-2(c^1 + c^2)}S \right].$$

(21)

By setting $x = S/p$, we can study the solutions of the equivalent equation

$$h(x) = x - \left[ 1 - 2e^{(c^1 + c^2)p}x + e^{-2(c^1 + c^2)p}x \right] = 0$$

(22)

in the $(c^1 p, c^2 p)$ parameter plane. Figure 2 shows the phase diagram of this model. Here, the red solid line indicates a line of hybrid first order phase transition points and the black dashed line indicates a line of second order phase transition points; the point $T$ is a tricritical point.
We compare the analytical solutions \( S(p) \) with numerical simulations in Fig. 3. There is good agreement where the transition is continuous. In the case of discontinuous transitions and close to the tricritical point, we observe finite size effects, with an improved agreement for larger network sizes.

The line of continuous phase transitions can be calculated analytically by imposing the condition that a nontrivial solution \( x^* \) > 0, satisfying \( h(x^*) = 0 \), goes to zero as a function of the parameter \( p \). Therefore, we expand \( h(x^*) \) for \( x^* = \varepsilon \ll 1 \) finding

\[
h(x^*) = h'(0)\varepsilon + \frac{1}{2}h''(0)\varepsilon^2 + \frac{1}{3!}h'''(0)\varepsilon^3 + O(\varepsilon^4). \tag{23}
\]

If \( h'(0) < 0 \) and \( h''(0) > 0 \), we find the following solution \( x^* = \varepsilon \ll 1 \) of Eq. (23):

\[
x^* = \varepsilon \propto (p - 1/c^3), \tag{24}
\]

implying

\[
S \propto (p - 1/c^3)^\beta \tag{25}
\]

with \( \beta = 1 \). This indicates that as long as \( h''(0) > 0 \) (i.e., \( c^2 > \sqrt{2}c \)) the points \( c^2p = 1 \) for which \( h'(0) = 0 \) are second order critical points.

At the point \( c^2/c^1 = \sqrt{2} \), we have \( h''(0) = 0 \). To find a nontrivial solution of Eq. (23) for \( p \approx p_c = 1/c^2 \) (in the following, we will use \( p_c \) as the generic critical value of \( p \) at a phase transition), we have to go up to the third order in the \( \varepsilon \) expansion, finding, since \( h'''(0) > 0 \),

\[
x^* = \varepsilon \propto (p - 1/c^3)^{1/2}, \tag{26}
\]

implying

\[
S \propto (p - 1/c^3)^\beta \tag{27}
\]

with \( \beta = \frac{1}{2} \). Therefore, the point \( c^2/c^1 = \sqrt{2} \), \( c^2p = 1 \) is the tricritical point \( T \). For \( c^2 < \sqrt{2}c^1 \) and \( c^2p < 1 \), we observe a line of first order phase transition points determined by the conditions \( h(x^*) = 0 \) and \( x^* > 0 \). The expansion of Eq. (21) at these transition points shows that \( \beta = \frac{1}{2} \), thus the transition is hybrid. Finally, we observe that in the case \( c^2 = 0 \) we have \( c^1p_c = 2.4554 \ldots \) recovering the result of two Poisson networks without overlap and with average degree \( c^1 \) [6].

From this simple model we observe several interesting features. First, we observe that increasing the overlap \( c^2 \) between the layers improves the robustness of the multiplex system and changes the order of the percolation phase transition from first order to second order in a smooth way (through a tricritical point). Moreover, the continuous phase transition is entirely driven by the (classical) percolation of the subnetwork of double edges \( (c^2p = 1) \). Finally, it is interesting to note that when the ratio \( c^1/c^2 \) is large enough, the percolating phase extends in a region where it can be \( c^2p < 1 \) (Fig. 2). This is not surprising, as it signals that the small overlap behavior takes over the overlap-driven percolating phase. In other words, on the right-hand side of the tricritical point \( T \) in Fig. 2, the MCGC is not simply containing a classical giant cluster entirely constituted by double edges, as this does not percolate on its own if \( c^2p < 1 \). Instead, a relevant fraction of pairs of nodes in the MCGC are connected by noncoincident paths of each type of edges. This is the scenario described, in the case of negligible edge overlap, in Ref. [30].

**B. Three Poisson layers with overlap**

As a second example, we consider the ensemble of a three-layer multiplex \( (M = 3) \) with Poisson multidegree distribution and \( \langle k^{100} \rangle = \langle k^{011} \rangle = \langle k^{010} \rangle = \langle k^{110} \rangle = \langle k^{101} \rangle = \langle k^{111} \rangle = c^3 \), and \( \langle k^{111} \rangle = c^3 \) (recall that 1, 2, 3 in \( c^3 \) are, as earlier, indices, not exponents). As in the previous case, we have just one order parameter \( S = S_m \) that satisfies the equation

\[
S = p[1 - 3e^{-(c^1+2c^2+c^3)}S + 3e^{-(2c^1+3c^2+c^3)}S - e^{-(3c^1+3c^2+c^3)}S]. \tag{28}
\]
FIG. 4. (Color online) The phase diagram of the three-layer multiplex with Poisson multidegree distribution parametrized by $c^1, c^2, c^3$. Below the plotted surface we have $S = 0$; above the surface we have $S > 0$.

By setting $x = S/p$, we can define a function $g(x)$ as

$$g(x) = x - \left[ 1 - 3e^{-(c^1 p + 2c^2 p + c^3 p)x} + 3e^{-(2c^1 p + 3c^2 p + c^3 p)x} - e^{-(3c^1 p + 3c^2 p + c^3 p)x} \right],$$

and we can recast the equation for $S$ as $g(x^*) = 0$.

The three-dimensional (3D) phase diagram is displayed in Fig. 4 for $c^3 p < 1$. Under the surface there is no percolation ($S = 0$), whereas above the surface we have $S > 0$. The blue surface at $c^3 p = 1$ corresponds to continuous transitions, and the pink surface at $c^3 p < 1$ represents discontinuous transitions.

Figure 5 displays a section of the same phase diagram at $c^3 p = 1$. This section is quite relevant, as it entirely contains the line of tricritical points, plotted as a dotted-dashed blue line. This line starts at point $U$ given by $c^1 p = 0$, $c^3 p = 1/\sqrt{6}$, $c^2 p = 1$ and terminates at a multicritical point $Q$ determined by the conditions $g(0) = g'(0) = g''(0) = g'''(0) = 0$ given by $c_0^1 p = 0.892,550, c_0^2 p = 0.158,562, c_0^3 p = 1$ (see Appendix for further details). The tricritical line is determined by the condition $g(0) = g'(0) = g''(0) = 0$ and is given by $c^3 p = \frac{1}{6}[-3c^1 p + \sqrt{6 + 9(c^1 p)^2}], c^3 p = 1$, with $c^3 p < c_0^3 p$. At $c^3 p > c_0^3 p$, the nature of the transition changes, as the relatively higher fraction of single edges drives the system into a behavior where the MCGC is mainly characterized by nodes connected by different paths on each layer (as in the case of nonoverlapping layers [30]). Therefore, the solid red line beyond point $Q$ represents the locus of points characterized by a discontinuous phase transition of the percolating phase into a critical $S = 0$ phase.

To further characterize these critical phenomena, it is also interesting to examine sections at fixed $c^2 p$ (Fig. 6), which essentially governs the fraction of double edges in the multiplex network. We can identify three characteristic topologies as $c^2 p$ varies, exemplified by the lines (1), (2), and (3) of Fig. 6. The two discriminating cases are characterized by (i) the multicritical point $Q$, and (ii) the end point $U$.

At small values of $c^2 p$, the MCGC can collapse either continuously or discontinuously, depending on the relative abundance of single and triple edges. If $c^3/c^1$ is smaller than the slope of the segment $OE$, random damage causes a discontinuous transition, whereas along the $c^3 p = 0$ line, for example, we recover the continuous phase transition of classical percolation as the three Poisson networks are coincident. The line of second order critical points (dashed black) is determined by the condition $g(0) = g'(0) = 0$, which implies $c^3 p = 1$. Similarly to the two-layer case, the continuous transition constitutes the classical percolation scenario and is entirely driven by the subnetwork of triple edges. This line stands as it encounters the line of discontinuous transitions at a point which depends on the value of $c^2 p$. Quite interestingly, the line of first order hybrid transitions extends into the region $c^3 p > 1$ and ends in a critical point $C$ defined by $g(x^*) = g'(x^*) = g''(x^*) = 0$ with $x^* > 0$. Indeed, there is a region of phase space such that if we fix $c^1, c^2$, and $c^3$ and we raise the value of $p$, we first cross a second order transition point as $S$ continuously grows to a small finite value, then we...
overlap in a duplex can both change the order of the phase transition from hybrid first order to second order, and improve the robustness of the system. We also show that in multiplexes with more than two layers the observed critical phenomena become remarkably complex, including the presence of high order multicritical points. On one hand, there may occur first order phase transitions between percolating phases with different strengths. On the other, it emerges that overlap of edges which do not involve all the layers can also change a continuous phase transition to a discontinuous one, making system reliability less predictable. This is a feature which may be relevant in the design of large scale infrastructures. Here, we stress that in real multiplexes, such as in online games [12], social networks [40], and epidemiology [37], the presence of link overlap is the norm rather than the exception. Therefore, this work represents an important step for characterizing the robustness properties of real multiplexes, and it is also likely to have an impact on the dynamic processes occurring on multiplex systems.

Note added. Recently, we came to know about two papers where percolation on two-layer Poisson graphs with overlap is studied [42,43].

ACKNOWLEDGMENT

D.C., J.Z., and J.G. acknowledge funding from Science Foundation Ireland (11/I1/1026) and the FET-Proactive project PLEXMATH and E.L. acknowledges funding from James Martin 21st Century Foundation Reference No LC1213-006x.

APPENDIX: CALCULATION OF THE CRITICAL POINTS
IN THE THREE-LAYER POISSON MULTIPLEX

We now calculate the critical points and exponents of the three-layer Poisson multiplex with \( k^{100} = (k^{010}) = (k^{101}) = 1 \), \( k^{110} = (k^{101}) = (k^{011}) = 2 \), and \( k^{111} = c^2 \). Let \( x^* > 0 \) be a solution of equation \( g(x) = 0 \) where the function \( g \) is defined in Eq. (29). In order to calculate the position of a continuous phase transition, we expand \( g(x^*) \) for \( x^* = \epsilon \ll 1 \) finding

\[
g(x^*) = g'(0)\epsilon + \frac{1}{2} g''(0)\epsilon^2 + \frac{1}{3!} g'''(0)\epsilon^3 + \frac{1}{4!} g''''(0)\epsilon^4 + \mathcal{O}(\epsilon^5), \tag{A1}\]

with

\[
g'(0) = 1 - c^3 p,
\]

\[
g''(0) = 3(c^1 p + c^2 p + c^3 p)^2 - 3(2c^1 p + 3c^2 p + c^3 p)^2
- (3c^1 p + 3c^2 p + c^3 p)^2,
\]

\[
g'''(0) = -3(3c^1 p + c^2 p + c^3 p)^3 + 3(2c^1 p + 3c^2 p + c^3 p)^3
- (3c^1 p + 3c^2 p + c^3 p)^3,
\]

\[
g''''(0) = 3(c^1 p + c^2 p + c^3 p)^4 - 3(2c^1 p + 3c^2 p + c^3 p)^4
- (3c^1 p + 3c^2 p + c^3 p)^4. \tag{A2}\]

The set of second order critical points is determined by the condition \( g'(0) = 0 \) and \( g''(0) > 0 \) with the additional condition that a first order phase transition has not already occurred in the multiplex. These conditions imply \( c^3 p = 1 \),

\[
\text{FIG. 7. (Color online) Behavior of the function } g(x) \text{ at the points } U, Q, C, \text{ and } E. \text{ The point } Q \text{ is characterized by the conditions } g(0) = g'(0) = g''(0) = 0. \text{ The points } C \text{ are characterized by the conditions } g(x^*) = g'(x^*) = g''(x^*) = 0 \text{ with } x^* > 0.
\]
and determine all the points in region I of Fig. 6 in the main text. Close to these transition points, for \( p \approx p_c = 1/c^3 \), we have \( g''(0) > 0 \), therefore, by using the expansion of \( g(x) \) given by Eq. (A1) we get

\[
x^* = \epsilon \propto (p - 1/c^3),
\]

implying

\[
S \propto (p - 1/c^3)^\beta
\]

with \( \beta = 1 \).

The line of tricritical points is determined by the conditions \( g'(0) = g''(0) = 0 \) and \( g'''(0) > 0 \) yielding

\[
c^1 p < \frac{3 + (3 - 2\sqrt{2})^{1/3} + (3 + 2\sqrt{2})^{1/3}}{6},
\]

\[
c^2 p = \frac{1}{6}[-3c^1 p + 6 + 9(c^1 p)^2], \quad c^3 p = 1.
\]

Close to these transition points, for \( p \approx p_c = 1/c^3 \), we have \( g'''(0) > 0 \), therefore, by using the expansion of \( g(x) \) given by Eq. (A1) we get

\[
x^* = \epsilon \propto (p - 1/c^3)^{1/3},
\]

implying

\[
S \propto (p - 1/c^3)^\beta
\]

with \( \beta = \frac{1}{3} \).

The multicritical point \( Q \) is determined by the conditions \( g'(0) = g''(0) = g'''(0) = 0 \) yielding

\[
c^1 \frac{c^1}{c^3} = \frac{3 + (3 - 2\sqrt{2})^{1/3} + (3 + 2\sqrt{2})^{1/3}}{6} = 0.89255 \ldots,
\]

\[
c^2 \frac{c^2}{c^3} = \frac{-2 + (4 - 2\sqrt{2})^{1/3} + (4 + 2\sqrt{2})^{1/3}}{6} = 0.158562 \ldots,
\]

\[
p = 1/c^3.
\]

Close to this transition point, for \( p \approx p_c = 1/c^3 \), we have \( g'''(0) > 0 \). Therefore, by using the expansion of \( g(x) \) given by Eq. (A1), we get

\[
x^* = \epsilon \propto (p - 1/c^3)^{1/3},
\]

implying

\[
S \propto (p - 1/c^3)^\beta
\]

with \( \beta = \frac{1}{3} \).

Regarding the critical points \( C \) occurring at \( x_c > 0 \), we have the conditions \( g(x_c) = g'(x_c) = g''(x_c) = 0 \). Let us define the following auxiliary function \( \Phi(y^1, y^2, y^3) \) (as throughout the paper, \( \alpha \) is a layer index, not an exponent, in variable \( y^\alpha \)):

\[
\Phi(y^1, y^2, y^3) = 1 - 3e^{-(y^1 + y^2 + y^3)} + 3e^{-(2y^1 + 3y^2 + 4y^3)} - e^{-(3y^1 + 3y^2 + 4y^3)}.
\]

Using function \( \Phi \), we can rewrite \( g(x) \) and its derivatives in the following way:

\[
g(x) = x - \Phi(c^1 px, c^2 px, c^3 px) = \frac{S}{p} - \Phi(c^1 S, c^2 S, c^3 S),
\]

\[
g'(x) = 1 - p \sum_i c^i \frac{\partial \Phi}{\partial y^i},
\]

\[
g''(x) = -p^2 \sum_{ij} c^i c^j \frac{\partial^2 \Phi}{\partial y^i \partial y^j}.
\]

So, the conditions \( g(x_c) = g'(x_c) = g''(x_c) = 0 \) defining a point \( C \) imply

\[
\frac{S_c}{p_c} = \Phi(c^1 S_c, c^2 S_c, c^3 S_c),
\]

\[
\sum_i c^i \frac{\partial \Phi}{\partial y^i} = \frac{1}{p_c},
\]

\[
\sum_{ij} c^i c^j \frac{\partial^2 \Phi}{\partial y^i \partial y^j} = 0.
\]

Now, let us expand Eq. (A12) by imposing \( S = S_c + \xi \) for \( \xi \to 0 \) and \( p = p_c + \delta \) for \( \delta \to 0 \). Substituting the expansion of \( \Phi \),

\[
\Phi[c^1 (S_c + \xi), c^2 (S_c + \xi), c^3 (S_c + \xi)] = \Phi(c^1 S_c, c^2 S_c, c^3 S_c) + \sum_i c^i \frac{\partial \Phi}{\partial y^i} \xi + \frac{1}{2} \sum_{ij} c^i c^j \frac{\partial^2 \Phi}{\partial y^i \partial y^j} \xi^2 + \frac{1}{6} \sum_{ijk} c^i c^j c^k \frac{\partial^3 \Phi}{\partial y^i \partial y^j \partial y^k} \xi^3 + O(\xi^4),
\]

and applying the conditions above, we get

\[
0 = S_c + \xi - (p_c + \delta) \left[ \frac{S_c}{p_c} + \frac{\xi}{p_c} + K_3 \xi^3 + O(\xi^4) \right],
\]

from which it yields

\[
\xi \sim \delta^{1/3}.
\]

Hence, we have \( \beta = \frac{1}{3} \).